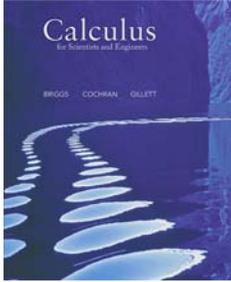


Chapter 6

Applications of Integration



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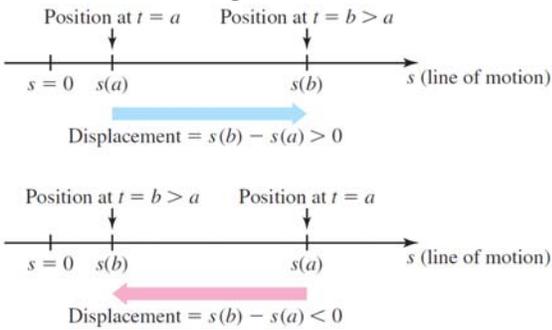
6.1

Velocity and Net Change

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1

Figure 6.1



Position at $t = a$ Position at $t = b > a$

$s = 0$ $s(a)$ $s(b)$ s (line of motion)

Displacement = $s(b) - s(a) > 0$

Position at $t = b > a$ Position at $t = a$

$s = 0$ $s(b)$ $s(a)$ s (line of motion)

Displacement = $s(b) - s(a) < 0$

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Figure 6.2 (a)

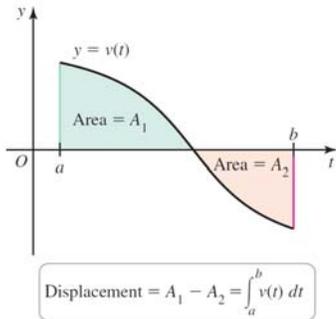
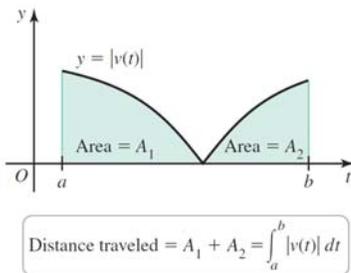


Figure 6.2 (b)



2

DEFINITION Position, Velocity, Displacement, and Distance

1. The **position** of an object moving along a line at time t , denoted $s(t)$, is the location of the object relative to the origin.
2. The **velocity** of an object at time t is $v(t) = s'(t)$.
3. The **displacement** of the object between $t = a$ and $t = b > a$ is

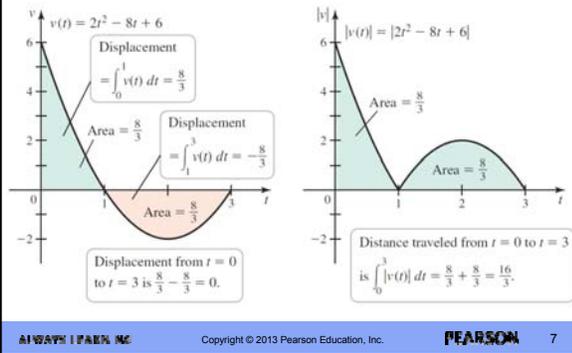
$$s(b) - s(a) = \int_a^b v(t) dt.$$

4. The **distance traveled** by the object between $t = a$ and $t = b > a$ is

$$\int_a^b |v(t)| dt.$$

where $|v(t)|$ is the **speed** of the object at time t .

Figure 6.3



THEOREM 6.1 Position from Velocity

Given the velocity $v(t)$ of an object moving along a line and its initial position $s(0)$, the position function of the object for future times $t \geq 0$ is

$$s(t) = \underbrace{s(0)}_{\substack{\text{position at} \\ \text{initial} \\ \text{time } t}} + \underbrace{\int_0^t v(x) dx}_{\substack{\text{displacement} \\ \text{over } [0, t]}}$$

3

Figure 6.4

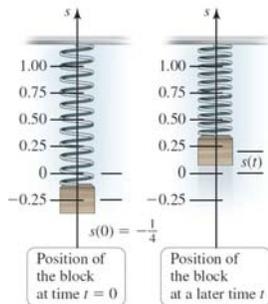


Figure 6.5 (a)

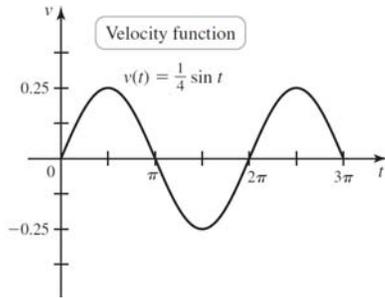
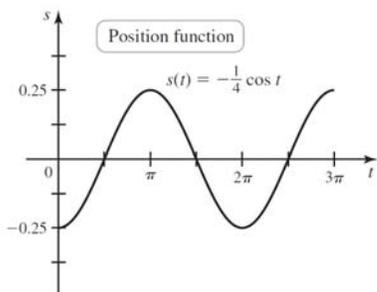
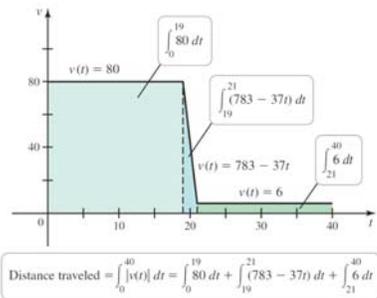


Figure 6.5 (b)



4

Figure 6.6

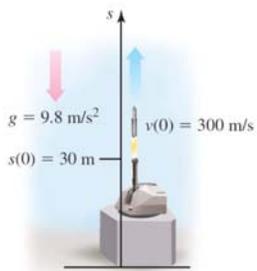


THEOREM 6.2 Velocity from Acceleration

Given the acceleration $a(t)$ of an object moving along a line and its initial velocity $v(0)$, the velocity of the object for future times $t \geq 0$ is

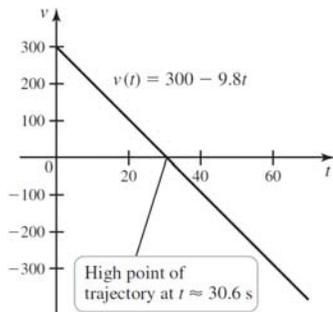
$$v(t) = v(0) + \int_0^t a(x) dx.$$

Figure 6.7



5

Figure 6.8



THEOREM 6.3 Net Change and Future Value

Suppose a quantity Q changes over time at a known rate Q' . Then the **net change** in Q between $t = a$ and $t = b$ is

$$\underbrace{Q(b) - Q(a)}_{\text{net change in } Q} = \int_a^b Q'(t) dt.$$

Given the initial value $Q(0)$, the **future value** of Q at time $t \geq 0$ is

$$Q(t) = Q(0) + \int_0^t Q'(x) dx.$$

Table 6.1

Velocity–Displacement Problems

Position $s(t)$

Velocity: $s'(t) = v(t)$

Displacement: $s(b) - s(a) = \int_a^b v(t) dt$

Future position: $s(t) = s(0) + \int_0^t v(x) dx$

General Problems

Quantity $Q(t)$ (such as volume or population size)

Rate of change: $Q'(t)$

Net change: $Q(b) - Q(a) = \int_a^b Q'(t) dt$

Future value of Q : $Q(t) = Q(0) + \int_0^t Q'(x) dx$

6

Figure 6.9

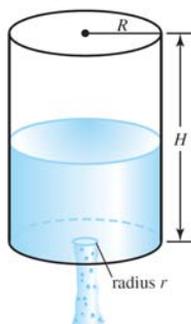
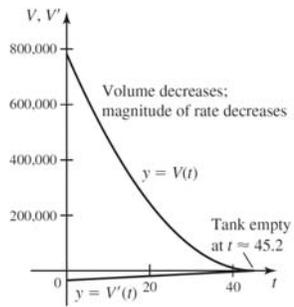


Figure 6.10



6.2

Regions Between Curves

7

Figure 6.11

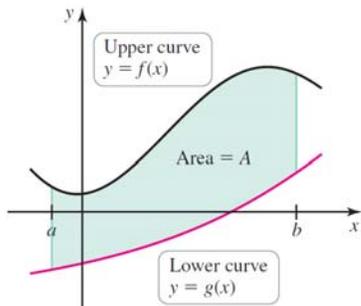


Figure 6.12

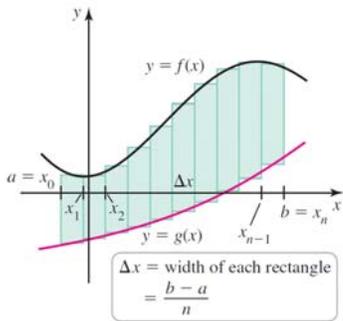
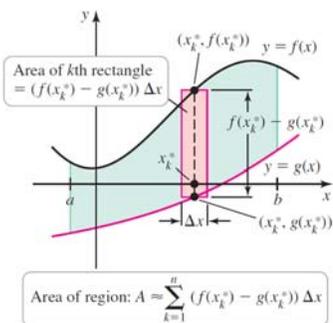


Figure 6.13



8

DEFINITION Area of a Region Between Two Curves

Suppose that f and g are continuous functions with $f(x) \geq g(x)$ on the interval $[a, b]$. The area of the region bounded by the graphs of f and g on $[a, b]$ is

$$A = \int_a^b (f(x) - g(x)) dx.$$

Figure 6.14

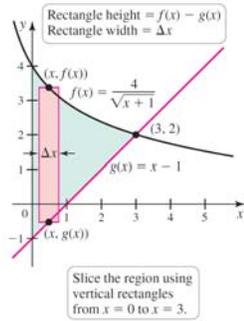
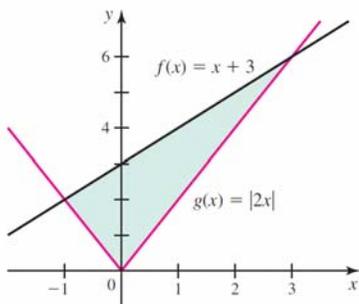


Figure 6.15 (a)



9

Figure 6.15 (b)

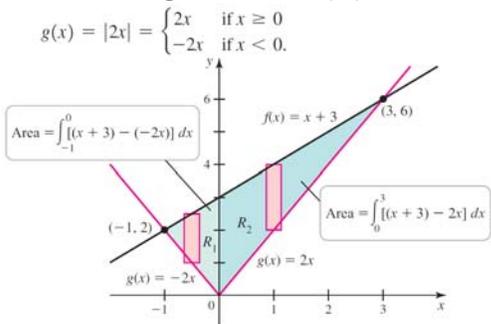


Figure 6.16

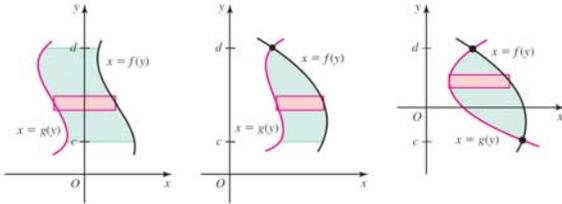
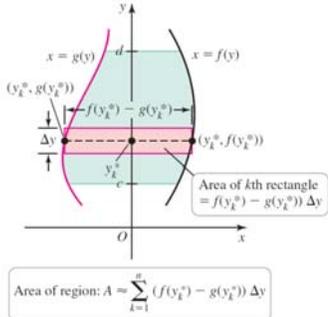


Figure 6.17



10

DEFINITION Area of a Region Between Two Curves with Respect to y
 Suppose that f and g are continuous functions with $f(y) \geq g(y)$ on the interval $[c, d]$.
 The area of the region bounded by the graphs $x = f(y)$ and $x = g(y)$ on $[c, d]$ is

$$A = \int_c^d (f(y) - g(y)) dy.$$

Figure 6.18

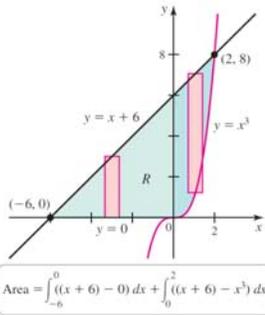
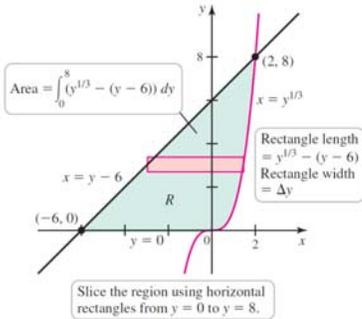


Figure 6.19



11

Figure 6.20

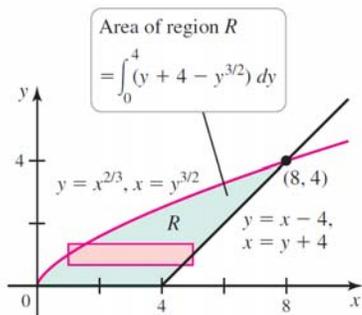
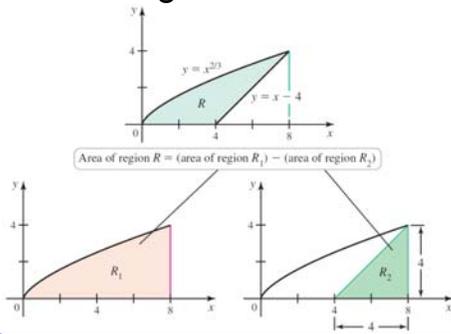


Figure 6.21



6.3

Volume by Slicing

12

Figure 6.22

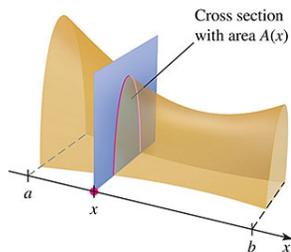


Figure 6.23

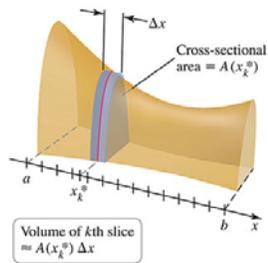
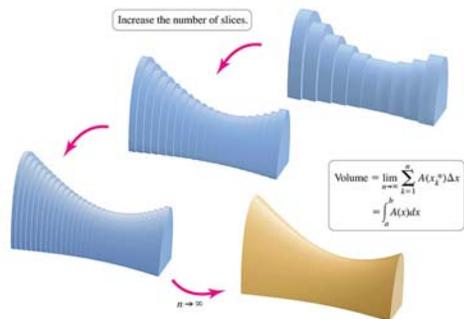


Figure 6.24



13

General Slicing Method

Suppose a solid object extends from $x = a$ to $x = b$ and the cross section of the solid perpendicular to the x -axis has an area given by a function A that is integrable on $[a, b]$. The volume of the solid is

$$V = \int_a^b A(x) dx.$$

Figure 6.25

$$r = \frac{1}{2}((2 - x^2) - x^2) = 1 - x^2.$$

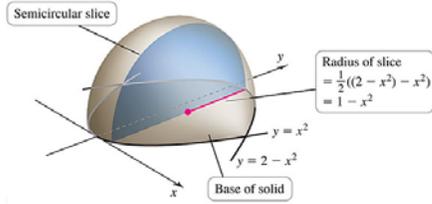
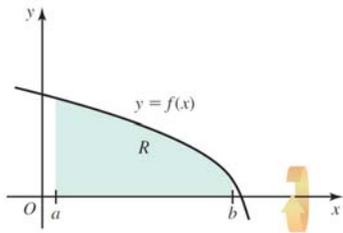
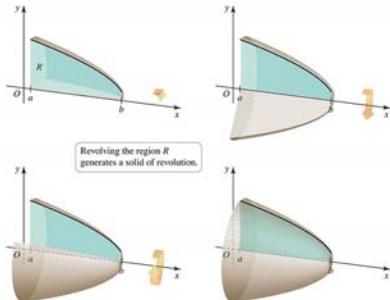


Figure 6.26



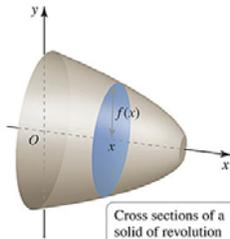
14

Figure 6.27



Revolving the region R generates a solid of revolution.

Figure 6.28



Cross sections of a solid of revolution are circular disks of radius $f(x)$ and area $\pi f(x)^2$.

Disk Method About the x -Axis

Let f be continuous with $f(x) \geq 0$ on the interval $[a, b]$. If the region R bounded by the graph of f , the x -axis, and the lines $x = a$ and $x = b$ is revolved about the x -axis, the volume of the resulting solid of revolution is

$$V = \int_a^b \pi f(x)^2 dx.$$

15

Figure 6.29 (1 of 2)

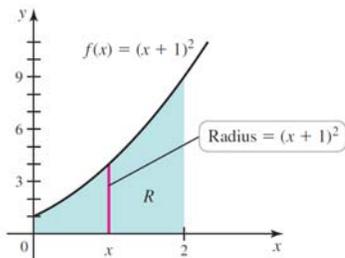


Figure 6.29 (2 of 2)

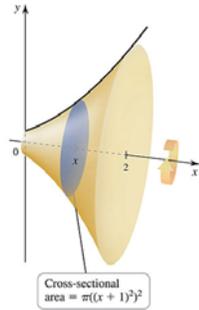
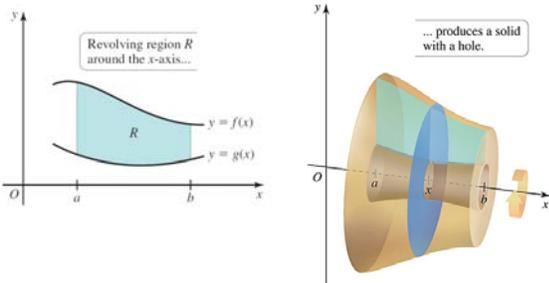
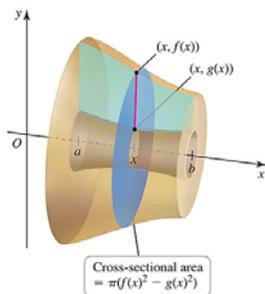


Figure 6.30



16

Figure 6.31

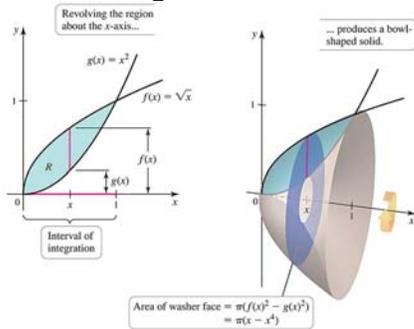


Washer Method About the x-Axis

Let f and g be continuous functions with $f(x) \geq g(x) \geq 0$ on $[a, b]$. Let R be the region bounded by $y = f(x)$, $y = g(x)$, and the lines $x = a$ and $x = b$. When R is revolved about the x -axis, the volume of the resulting solid of revolution is

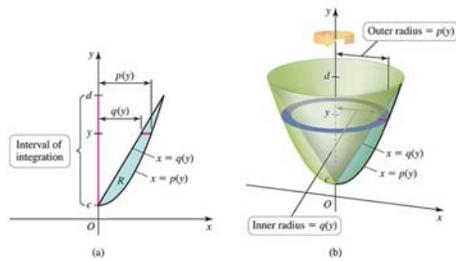
$$V = \int_a^b \pi(f(x)^2 - g(x)^2) dx.$$

Figure 6.32



17

Figure 6.33 (a & b)



Disk and Washer Methods About the y-Axis

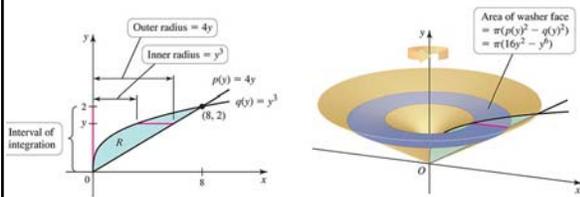
Let p and q be continuous functions with $p(y) \geq q(y) \geq 0$ on $[c, d]$. Let R be the region bounded by $x = p(y)$, $x = q(y)$, and the lines $y = c$ and $y = d$. When R is revolved about the y -axis, the volume of the resulting solid of revolution is given by

$$V = \int_c^d \pi(p(y)^2 - q(y)^2) dy.$$

If $q(y) = 0$, the disk method results:

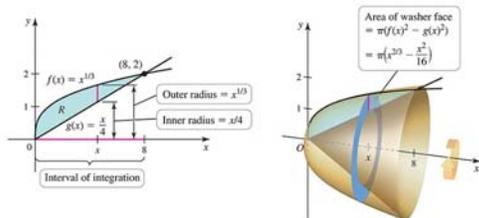
$$V = \int_c^d \pi p(y)^2 dy.$$

Figure 6.34



18

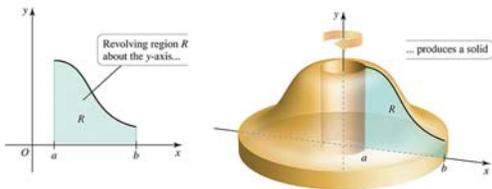
Figure 6.35



6.4

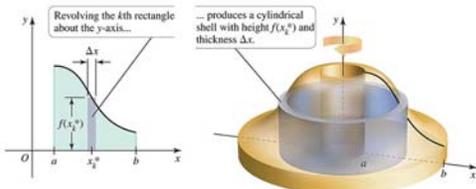
Volume by Shells

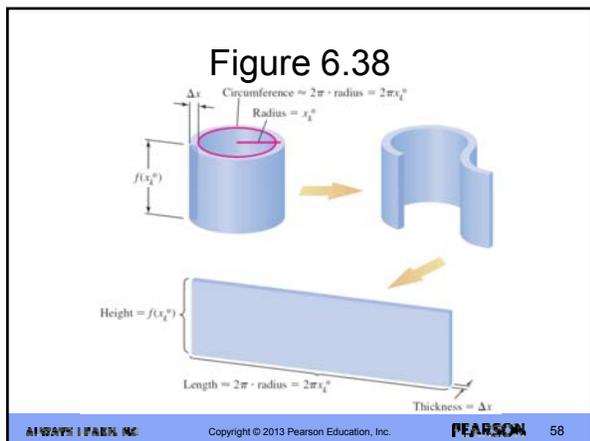
Figure 6.36

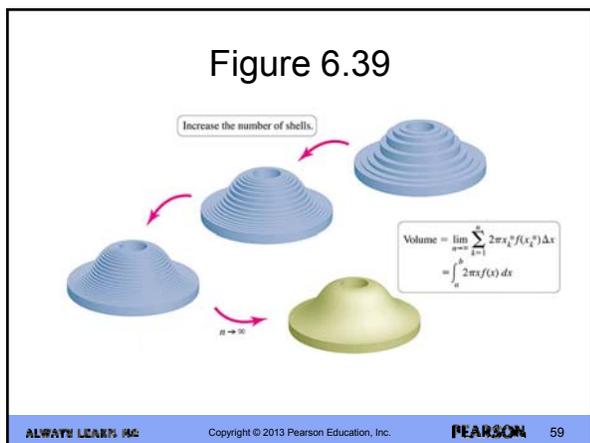


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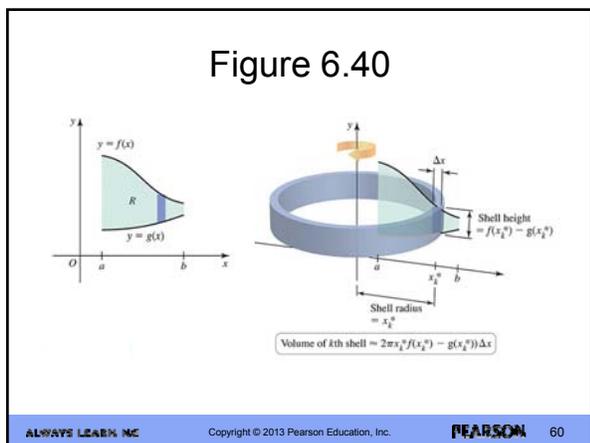
Figure 6.37







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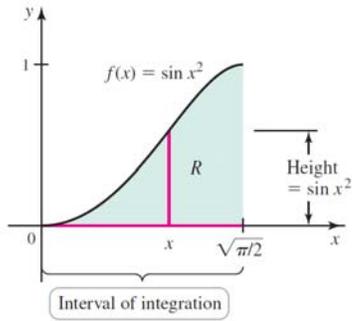


Volume by the Shell Method

Let f and g be continuous functions with $f(x) \geq g(x)$ on $[a, b]$. If R is the region bounded by the curves $y = f(x)$ and $y = g(x)$ between the lines $x = a$ and $x = b$, the volume of the solid generated when R is revolved about the y -axis is

$$V = \int_a^b 2\pi x(f(x) - g(x)) dx.$$

Figure 6.41



21

Figure 6.42

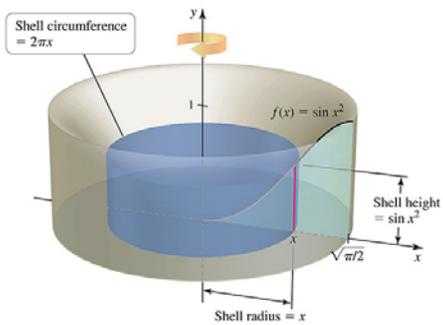


Figure 6.43

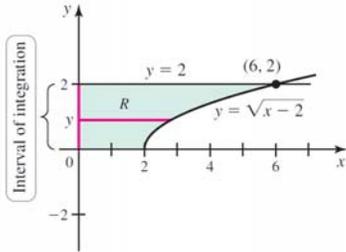
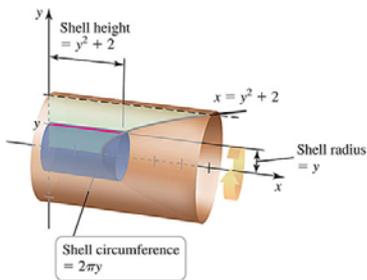


Figure 6.44



22

Figure 6.45 (a & b)

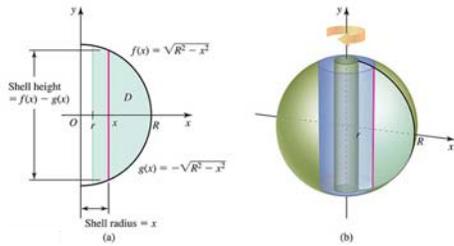


Figure 6.46 (a)

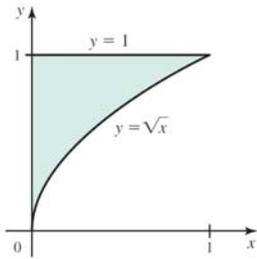
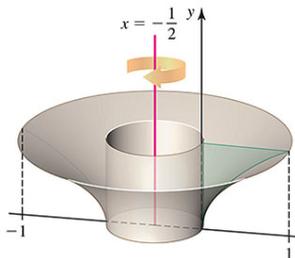


Figure 6.46 (b)



23

Figure 6.46 (c)

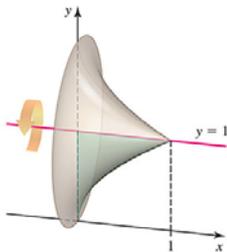


Figure 6.47

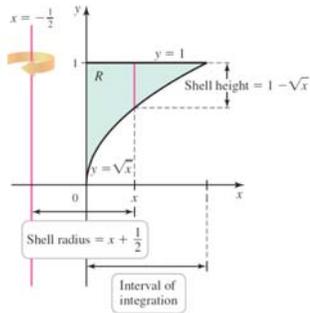
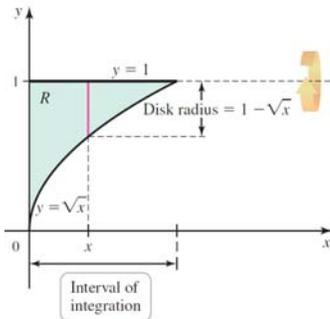


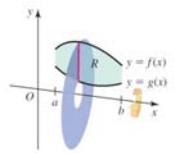
Figure 6.48



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Summary: Disk/Washer and Shell Methods *continued...*

Integration with respect to x

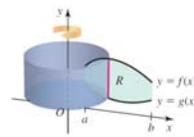


Disk/washer method about the x -axis
Disks/washers are *perpendicular* to the x -axis.

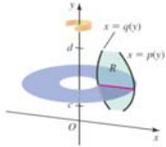
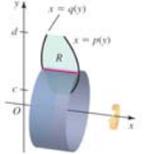
$$\int_a^b \pi(f(x)^2 - g(x)^2) dx$$

Shell method about the y -axis
Shells are *parallel* to the y -axis.

$$\int_a^b 2\pi x(f(x) - g(x)) dx$$

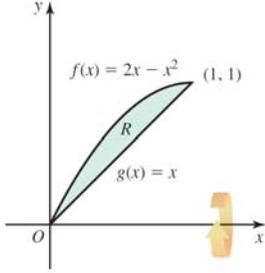


Summary: Disk/Washer and Shell Methods

<p>Integration with respect to y</p> 	<p>Disk/washer method about the y-axis Disks/washers are <i>perpendicular</i> to the y-axis.</p> $\int_c^d \pi(p(y)^2 - q(y)^2) dy$
	<p>Shell method about the x-axis Shells are <i>parallel</i> to the x-axis.</p> $\int_c^d 2\pi y(p(y) - q(y)) dy$

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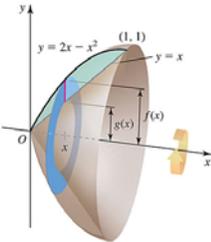
Figure 6.49



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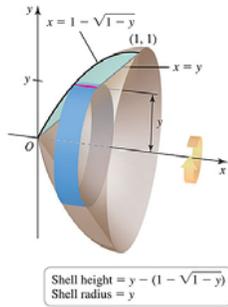
Figure 6.50



(Outer radius)² = (2x - x²)²
 (Inner radius)² = x²

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Figure 6.51



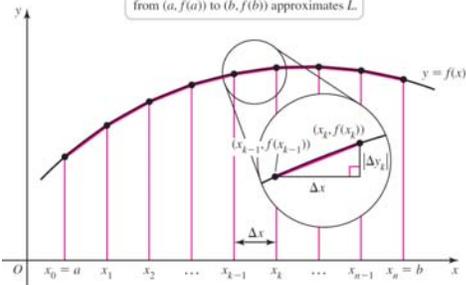
6.5

Length of Curves

26

Figure 6.52

The length of the red polygonal line from $(a, f(a))$ to $(b, f(b))$ approximates L .

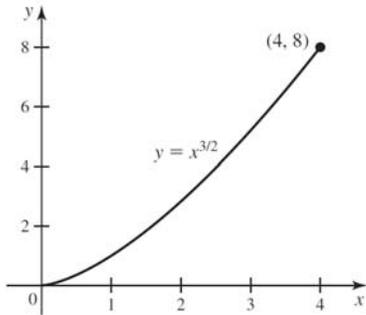


DEFINITION Arc Length for $y = f(x)$

Let f have a continuous first derivative on the interval $[a, b]$. The length of the curve from $(a, f(a))$ to $(b, f(b))$ is

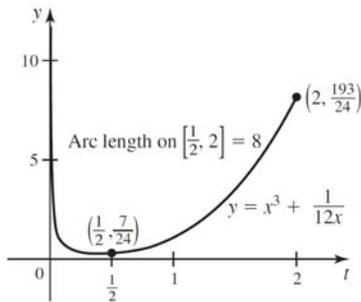
$$L = \int_a^b \sqrt{1 + f'(x)^2} dx.$$

Figure 6.53



27

Figure 6.54

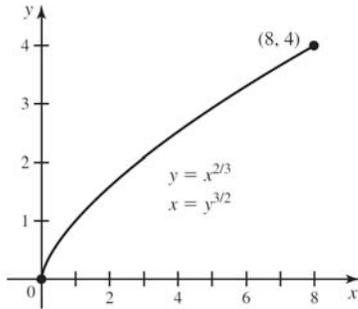


DEFINITION Arc Length for $x = g(y)$

Let $x = g(y)$ have a continuous first derivative on the interval $[c, d]$. The length of the curve from $(g(c), c)$ to $(g(d), d)$ is

$$L = \int_c^d \sqrt{1 + g'(y)^2} dy.$$

Figure 6.55



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6.6

Surface Area

Figure 6.56

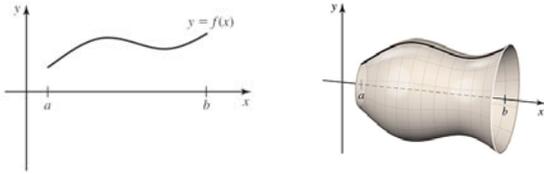
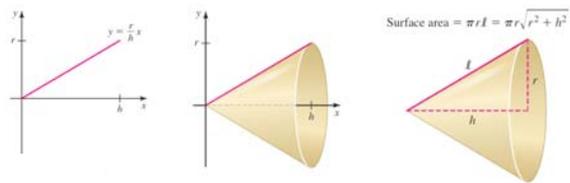


Figure 6.57



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Figure 6.58

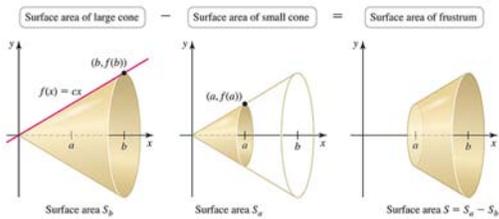


Figure 6.59

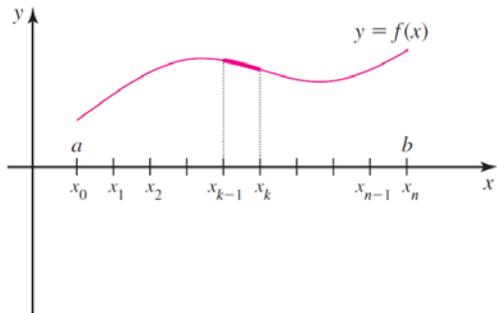
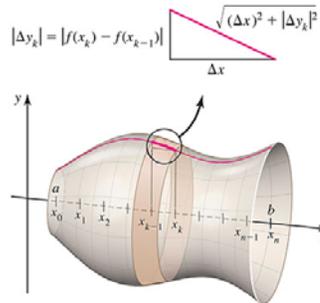


Figure 6.60



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DEFINITION Area of a Surface of Revolution

Let f be differentiable and positive on the interval $[a, b]$. The area of the surface generated when the graph of f on the interval $[a, b]$ is revolved about the x -axis is

$$S = \int_a^b 2\pi f(x) \sqrt{1 + f'(x)^2} dx.$$

Figure 6.61

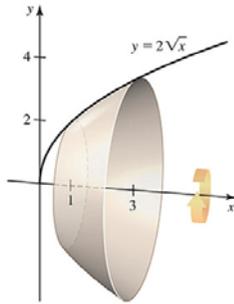
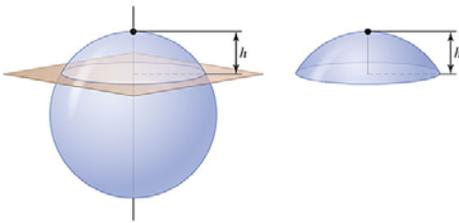


Figure 6.62



31

Figure 6.63

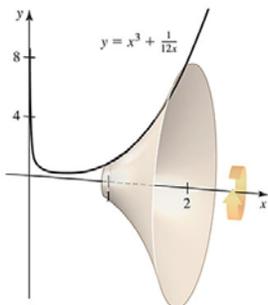
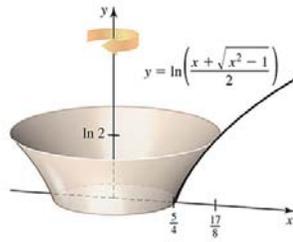


Figure 6.64



6.7

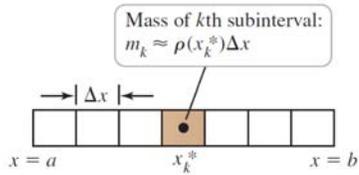
Physical Applications

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Figure 6.65



Figure 6.66



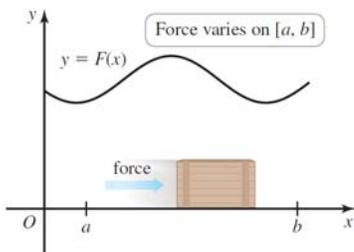
DEFINITION Mass of a One-Dimensional Object

Suppose a thin bar or wire is represented by a line segment on the interval $a \leq x \leq b$ with a density function ρ (with units of mass per length). The mass of the object is

$$m = \int_a^b \rho(x) dx.$$

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Figure 6.67

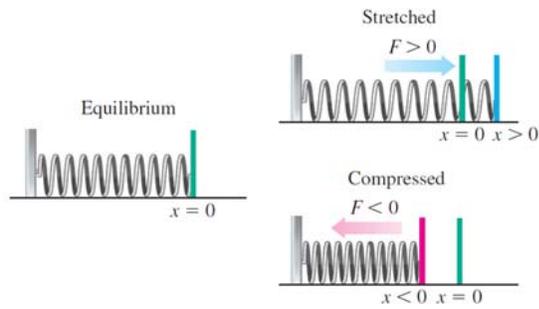


DEFINITION Work

The work done by a variable force F in moving an object along a line from $x = a$ to $x = b$ in the direction of the force is

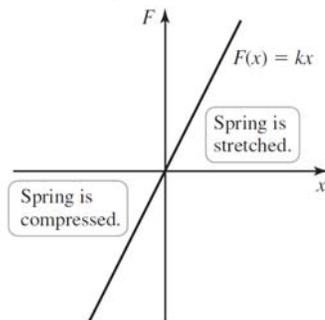
$$W = \int_a^b F(x) dx.$$

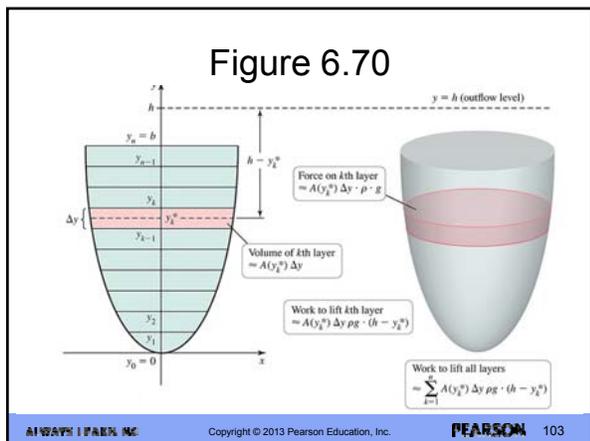
Figure 6.68



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Figure 6.69





PROCEDURE Solving Lifting Problems

1. Draw a y -axis in the vertical direction (parallel to gravity) and choose a convenient origin. Assume the interval $[a, b]$ corresponds to the vertical extent of the fluid.
2. For $a \leq y \leq b$, find the cross-sectional area $A(y)$ of the horizontal slices and the distance $D(y)$ the slices must be lifted.
3. The work required to lift the water is

$$W = \int_a^b \rho g A(y) D(y) dy.$$

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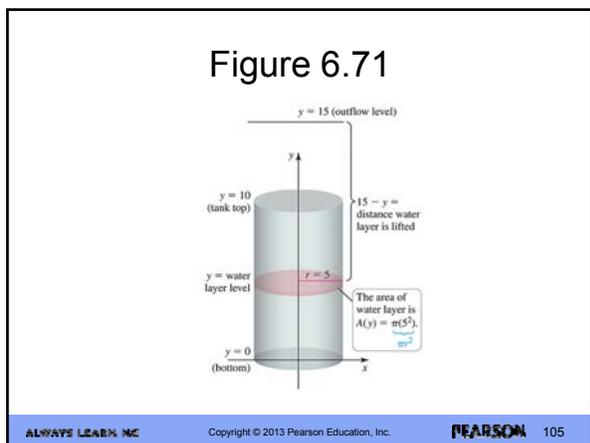


Figure 6.72

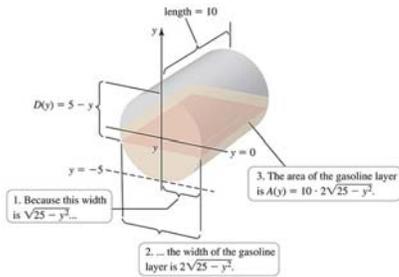
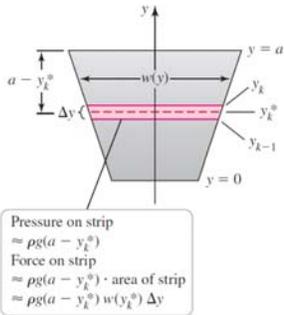


Figure 6.73



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PROCEDURE Solving Force/Pressure Problems

1. Draw a y -axis on the face of the dam in the vertical direction and choose a convenient origin (often taken to be the base of the dam).
2. Find the width function $w(y)$ for each value of y on the face of the dam.
3. If the base of the dam is at $y = 0$ and the top of the dam is at $y = a$, then the total force on the dam is

$$F = \int_0^a \underbrace{\rho g(a - y)}_{\text{depth}} \underbrace{w(y)}_{\text{width}} dy.$$

Figure 6.74

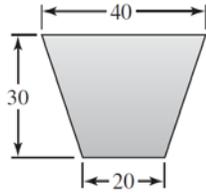
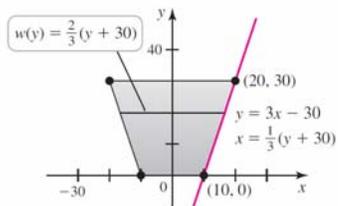


Figure 6.75



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